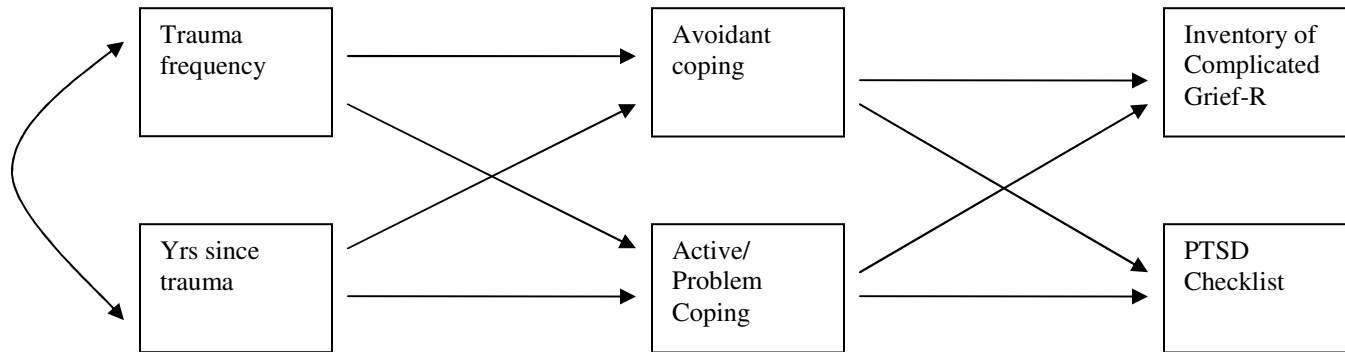


Hypothesized model (observed vars and paths only)



Hypothesized model (with variances and disturbances)

